# Convexity techniques for BSDEs from utility indifference valuation

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based on joint work with Christoph Frei, Semyon Malamud (ETH Zürich)

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Getting started

Getting into business Getting useful Getting done The basic problem Precise formulation Motivation

# The basic problem

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### Setup

• Starting point: Backward stochastic differential equation (BSDE)

$$\Gamma_s = G - \int_s^T g(Z_r) \, dr + \int_s^T Z_r \, dB_r, \quad 0 \le s \le T$$

with fully quadratic driver

$$g(z) = \chi + (z + \alpha)' \Lambda^{-1} (z + \alpha).$$

- Data: final condition G and driver  $g = (\Lambda, \alpha, \chi)$  with matrix  $\Lambda$ , vector  $\alpha$  and scalar  $\chi$ .
- **Solution:** pair (Γ, Z) with scalar Γ and vector Z; driving Brownian motion B is also vector.
- Everything happens on  $(\Omega, \mathcal{F}, I\!\!\!F, P)$ .

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### Questions

- Main question: What happens if
  - we change the probability measure P ?
  - we change the filtration # ?
  - we change the underlying space  $\Omega$  ?
- Can we somehow generate and/or exploit symmetry?

• Idea:

- Basic BSDE gives exact description of problem and solution, but often hard to solve.
- Can we replace it by simpler BSDE ?
- Can we even find another BSDE with explicit solution  $\tilde{\Gamma}$  ...?
- ... and then estimate  $\Gamma$  in terms of  $\tilde{\Gamma}$  ?

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# **Precise formulation**

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### The BSDE

### • Basic BSDE is

$$d\Gamma_s = (\chi_s + (Z_s + \alpha_s)'\Lambda_s^{-1}(Z_s + \alpha_s)) ds - Z_s dB_s,$$
  
$$\Gamma_T = G.$$

### • Assumptions:

- $G, \Lambda, \alpha, \chi$  are all uniformly bounded.
- $\Lambda$  has eigenvalues uniformly bounded away from 0 and  $\infty.$
- Solution: pair  $(\Gamma, Z)$  with
  - $\Gamma$  bounded semimartingale.
  - Z integrand for Brownian motion B in  $\mathbb{R}^n$ .
- Explicit formula: if  $\Lambda = c \operatorname{I}_{n \times n}$  and  $\alpha \equiv 0$ ,  $\chi \equiv 0$ , then

$$\Gamma_s = -c \log E[\exp(-G/c) | \mathcal{F}_s].$$

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### Basic results

#### • Basic BSDE is

$$d\Gamma_s = (\chi_s + (Z_s + \alpha_s)'\Lambda_s^{-1}(Z_s + \alpha_s)) ds - Z_s dB_s,$$
  
$$\Gamma_T = G.$$

- Basic BSDE has unique solution  $(\Gamma, Z)$ .
- For any solution  $(\Gamma, Z)$  with  $\Gamma$  bounded, Z is in BMO(B).
- Key property: The function (A, z) → f(A, z) = z'A<sup>-1</sup>z in the driver is (jointly) convex.
- Γ from solution (Γ, Z) of basic BSDE is jointly concave as a function of (G, Λ, α, χ).
- → Kobylanski (2000), Mania/S (2005)

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# **Some motivation**

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### PDE motivation

Start with PDE

$$u_s + \frac{1}{2}\Delta u - f(\Lambda, \alpha - \nabla u) - \chi = 0, \quad u(T, x) = h(x).$$

### • Link to BSDE: solution to BSDE is $\Gamma_{\cdot} = u(\cdot, B_{\cdot}),$ $Z_{\cdot} = -\nabla u(\cdot, B_{\cdot}).$

# • Symmetrise: $\tilde{\Lambda} := \frac{1}{n!} \sum_{O \in \text{Perm}} O' \Lambda O, \ \tilde{\alpha} := \frac{1}{n!} \sum_{O \in \text{Perm}} O' \alpha,$ $\tilde{h} := \frac{1}{n!} \sum_{O \in \text{Perm}} h \circ O.$

• Symmetrised PDE then reads

$$ilde{u}_s + rac{1}{2}\Delta ilde{u} - f( ilde{\Lambda}, ilde{lpha} - 
abla ilde{u}) - \chi = 0, \quad ilde{u}( au, x) = ilde{h}(x).$$

• Comparison result:  $\tilde{u}(0,0) \ge u(0,0)$ .

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### Argument

• Replace x by Ox and compute to get

$$f(\Lambda, \alpha - O\nabla u(s, Ox)) = f(O'\Lambda O, O'\alpha - \nabla u(s, Ox)).$$

• Symmetrised function  $\bar{u}(s,x) := \frac{1}{n!} \sum_{O \in \text{Perm}} u(s,Ox)$  solves

$$\begin{split} \bar{u}_s(s,x) + \frac{1}{2}\Delta \bar{u}(s,x) - \chi - \frac{1}{n!} \sum_{O \in \text{Perm}} f(O' \wedge O, O' \alpha - \nabla u(s, Ox)) &= 0, \\ \bar{u}(T,x) &= \tilde{h}(x). \end{split}$$

• By joint **convexity** of *f*,

f

$$\frac{1}{n!}\sum_{O\in\operatorname{Perm}}f(O'\Lambda O,O'\alpha-\nabla u(s,Ox))\geq f\big(\tilde{\Lambda},\tilde{\alpha}-\nabla \bar{u}(s,x)\big).$$

• So  $\tilde{u}(0,0) \geq \bar{u}(0,0) = u(0,0).$ 

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# Changing basics of BSDEs

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# Changing the measure

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### Setup and notations

- Key idea: parametric family of measures via Girsanov.
- Parameters for measure change are from suitable space *K* of processes κ (integrability conditions):

• 
$$dP^{\kappa} = \mathcal{E}\left(-\int \kappa \, dB\right) \, dP.$$

- $B^{\kappa} = B + \int \kappa_s ds$  is  $P^{\kappa}$ -Brownian motion.
- Auxiliary variables

$$G^{\kappa} := G - \int_{0}^{T} (\chi_{s} + \frac{1}{2}\kappa'_{s}\Lambda_{s}\kappa_{s}) ds - \int_{0}^{T} (\alpha_{s} + \Lambda_{s}\kappa_{s}) dB_{s}$$
$$= G - \int_{0}^{T} \chi_{s} ds - \int_{0}^{T} \alpha_{s} dB_{s} - \int_{0}^{T} \kappa_{s} dB_{s} - \frac{1}{2} \int_{0}^{T} \kappa'_{s}\Lambda_{s}\kappa_{s} ds.$$

• Important quantities:  $\delta^{\max} := \sup_{0 \le s \le T} \|\max \operatorname{spec}(\Lambda_s)\|_{\infty}$ ,  $\delta^{\min} := \inf_{0 \le s \le T} \frac{1}{\|\max \operatorname{spec}(\Lambda_s^{-1})\|_{\infty}}.$ 

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### Varying the measure

### • Theorem 1:

$$\Gamma_t = - \operatorname{ess \ sup \ log \ } E_{P^{\kappa}} [\exp(-G_t^{\kappa}/\delta_t^{\max}) \,|\, \mathcal{F}_t]^{\delta_t^{\max}}$$

$$= - \operatorname{ess\,inf\,log} E_{P^{\kappa}}[\exp(-G_t^{\kappa}/\delta_t^{\min}) \,|\, \mathcal{F}_t]^{\delta_t^{\min}},$$

and for every  $\kappa \in \mathcal{K}$ ,

$$\Gamma_t = \log E_{P^\kappa} [\exp(-G_t^\kappa/\delta) \,|\, \mathcal{F}_t]^\delta \Big|_{\delta = \delta_t^{\kappa,G}}$$

for some  $\mathcal{F}_t$ -measurable  $\delta_t^{\kappa,G}$  with values in  $[\delta_t^{\min}, \delta_t^{\max}]$ . • Comments:

- Quasi-explicit structural formula via interpolation.
- Upper and lower bounds for  $\Gamma_t$  via choices of  $\kappa$ .
- Key quantities are extremal eigenvalues of Λ.

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### Outline of proof 1

• Explicitly, 
$$\Gamma^{\delta,\kappa}:=-\log E_{P^\kappa}[\exp(-\cdot/\delta)|I\!\!\!/]^\delta$$
 has dynamics

$$d\Gamma^{\delta,\kappa}=\frac{1}{2\delta}|Z^{\delta,\kappa}|^2\,dt-Z^{\delta,\kappa}\,dB^{\kappa}.$$

• Under  $P^{\kappa}$ ,  $\Gamma$  has dynamics

$$d\Gamma = \frac{1}{2}(Z + \alpha + \Lambda \kappa)' \Lambda^{-1}(Z + \alpha + \Lambda \kappa) dt + (\chi - \kappa' \alpha - \frac{1}{2} \kappa' \Lambda \kappa) dt - Z dB^{\kappa},$$

and first dt-term is, by estimating eigenvalues,

$$\geq \frac{1}{2\delta^{\max}} |Z + \alpha + \Lambda \kappa|^2 \, dt.$$

Rewrite

$$\begin{aligned} -Z \, dB^{\kappa} &= -(Z + \alpha + \Lambda \kappa) \, dB^{\kappa} + (\alpha + \Lambda \kappa) \, dB^{\kappa} \\ &= -(Z + \alpha + \Lambda \kappa) \, dB^{\kappa} + (\alpha + \Lambda \kappa) \, dB \\ &+ (\alpha' \kappa + \kappa' \Lambda \kappa) \, dt. \end{aligned}$$

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### Outline of proof 2

• Put things together to obtain

$$egin{array}{rcl} d\Gamma &\geq & rac{1}{2\delta^{\max}}|Z+lpha+\Lambda\kappa|^2\,dt-(Z+lpha+\Lambda\kappa)\,dB^\kappa\ &+(\chi+rac{1}{2}\kappa'\Lambda\kappa)\,dt+(lpha+\Lambda\kappa)\,dB. \end{array}$$

• Recall 
$$d\Gamma^{\delta,\kappa} = rac{1}{2\delta} |Z^{\delta,\kappa}|^2 dt - Z^{\delta,\kappa} dB^{\kappa}.$$

• Final value of original  $\Gamma$  is  $\Gamma_T = G$ . Using for BSDE inequality instead final value

$$G - \int_{t}^{T} \left( \left( \chi_{s} + \frac{1}{2} \kappa_{s}^{\prime} \Lambda_{s} \kappa_{s} \right) ds + \left( \alpha_{s} + \Lambda_{s} \kappa_{s} \right) dB_{s} \right) = G_{t}^{\kappa}$$

therefore gives  $\Gamma_t \leq \Gamma_t^{\delta_t^{\max,\kappa}}$  from **BSDE comparison**.

• Equality for choice of  $\kappa$  with  $Z + \alpha + \Lambda \kappa = 0$ .

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# **Changing the filtration**

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### Setup and notations

- Key idea: split space into subspaces with  $n = \overline{n} + \underline{n}$ . Then project on upper half.
- Brownian motion  $B = (\overline{B}, \underline{B})$  in  $\mathbb{R}^n = \mathbb{R}^{\overline{n}} \times \mathbb{R}^{\underline{n}}$ .
- Filtrations  $F = F^B$ ,  $\overline{F} = F^{\overline{B}}$ ,  $\underline{F} = F^{\underline{B}}$ .
- Generators  $g, \overline{g}$  with  $f(A, z) = z'A^{-1}z$  and  $\overline{f}(\overline{A}, \overline{z}) = \overline{z}'\overline{A}^{-1}\overline{z}$ , where  $\overline{A}$  is the upper left  $\overline{n} \times \overline{n}$  corner of A.
- Final values G and  $\overline{G} = E[G | \overline{\mathcal{F}}_T]$ .

BSDEs

$$d\Gamma_{s} = (\chi_{s} + f(\Lambda_{s}, Z_{s} + \alpha_{s})) ds - Z_{s} dB_{s}, \quad \Gamma_{T} = G$$

and

$$d\check{\Gamma}_{s} = \left(\chi_{s}^{o} + \overline{f}(\overline{\Lambda}_{s}^{o}, \check{Z}_{s} + \overline{\alpha}_{s}^{o})\right) ds - \check{Z}_{s} d\overline{B}_{s}, \quad \check{\Gamma}_{T} = \overline{G}.$$

• Superscript <sup>o</sup> for **optional projection** under P on  $\overline{F}$ .

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### Shrinking the filtration

• Theorem 2: For the solutions  $(\Gamma, Z)$  and  $(\check{\Gamma}, \check{Z})$  of the BSDEs

$$d\Gamma_{s} = (\chi_{s} + f(\Lambda_{s}, Z_{s} + \alpha_{s})) ds - Z_{s} dB_{s}, \quad \Gamma_{T} = G$$

and

$$d\check{\Gamma}_{s} = \left(\chi_{s}^{o} + \overline{f}(\overline{\Lambda}_{s}^{o}, \check{Z}_{s} + \overline{\alpha}_{s}^{o})\right) ds - \check{Z}_{s} d\overline{B}_{s}, \quad \check{\Gamma}_{T} = \overline{G}.$$

we have

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$$\Gamma^{o} \leq \check{\Gamma}.$$

#### • Comments:

- Jensen-type inequality for our class of BSDEs.
- In simplest case,  $\Gamma_0 = -c \log E[\exp(-G/c)]$  and

$$\check{\Gamma}_0 = -c \log E[\exp(-\overline{G}/c)], \text{ with } \overline{G} = E[G | \overline{\mathcal{F}}_T]$$

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## Outline of proof

•  $(\Gamma, Z)$  solves BSDE

$$d\Gamma_s = (\chi_s + f(\Lambda_s, Z_s + \alpha_s)) ds - Z_s dB_s, \quad \Gamma_T = G.$$

• Projecting on filtration  $\overline{I\!\!F}$  gives

$$d\Gamma_s^o = \left(\chi_s^o + f(\Lambda_s, Z_s + \alpha_s)\right)^o ds - Z_s^o d\overline{B}_s, \quad \Gamma_T^o = \overline{G}.$$

• Convexity of f yields

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$$(f(\Lambda_s, Z_s + \alpha_s))^o \ge f(\Lambda_s^o, Z_s^o + \alpha_s^o),$$

and  $f(A, z) \ge \overline{f}(\overline{A}, \overline{z})$ . •  $(\check{\Gamma}, \check{Z})$  solves BSDE

$$d\check{\Gamma}_{s} = \left(\chi_{s}^{o} + \overline{f}(\overline{\Lambda}_{s}^{o}, \check{Z}_{s} + \overline{\alpha}_{s}^{o})\right) ds - \check{Z}_{s} d\overline{B}_{s}, \quad \check{\Gamma}_{T} = \overline{G},$$

Result follows from BSDE comparison theorem.

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# Changing the underlying space

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### Setup and notations

- Key idea: normal distribution is rotation-invariant; so can transform Brownian increments without doing harm.
- $\Omega = C([0, T]; \mathbb{R}^n)$  Wiener space with Wiener measure P.
- For  $u \in \mathbf{O}(n)$  and fixed t, define transformation on  $\Omega$  by

$$U_t(g)(s) := \left\{egin{array}{ll} \omega(s) & ext{for } s \leq t, \ \omega(t) + uig(g\omega(s) - \omega(t)ig) & ext{for } s > t. \end{array}
ight.$$

(rotate increments after time t by u).

- Key point: Wiener measure and transformation U<sub>t</sub> commute; so
  - $B^u := U_t \circ B$  is again Brownian motion.
  - $B \circ U_t = U_t \circ B$ .
  - $\int (Z \circ U_t) dB^u = (\int Z dB) \circ U_t$ , i.e., stochastic integrals also "commute" with  $U_t$ .

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### Transforming Wiener space

• Theorem 3: If general BSDE

$$\Gamma_s = G - \int_s^T F_r(\Gamma_r, Z_r) \, dr + \int_s^T Z_r \, dB_r$$

has unique solution  $(\Gamma, Z)$ , then transformation  $(\Gamma \circ U_t, Z \circ U_t)$  is unique solution of transformed BSDE

$$\tilde{\Gamma}_{s} = G \circ U_{t} - \int_{s}^{T} (F \circ U_{t})_{r} (\tilde{\Gamma}_{r}, \tilde{Z}_{r}) dr + \int_{s}^{T} \tilde{Z}_{r} d(B \circ U_{t})_{r}.$$

In particular: Transformed solution  $(\Gamma \circ U_t, Z \circ U_t)$  agrees with  $(\Gamma, Z)$  on  $[\![0, t]\!]$ .

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### Averaging

• Back to our basic BSDE

$$d\Gamma_{s} = (\chi_{s} + f(\Lambda_{s}, Z_{s} + \alpha_{s})) ds - Z_{s} dB_{s}, \quad \Gamma_{T} = G.$$

• For finite subset  $\mathcal{O}$  of  $\mathbf{O}(n)$ , average parameters

$$\begin{split} G^{\mathcal{O}} &:= \frac{1}{|\mathcal{O}|} \sum_{u \in \mathcal{O}} G \circ U_t, \ \Lambda^{\mathcal{O}} &:= \frac{1}{|\mathcal{O}|} \sum_{u \in \mathcal{O}} u' (\Lambda \circ U_t) u, \\ \alpha^{\mathcal{O}} &:= \frac{1}{|\mathcal{O}|} \sum_{u \in \mathcal{O}} u' (\alpha \circ U_t), \ \chi^{\mathcal{O}} &:= \frac{1}{|\mathcal{O}|} \sum_{u \in \mathcal{O}} \chi \circ U_t. \end{split}$$

• **Corollary:** For solution  $(\Gamma^{\mathcal{O}}, Z^{\mathcal{O}})$  of BSDE

$$d\tilde{\Gamma}_{s} = \left(\chi_{s}^{\mathcal{O}} + f(\Lambda_{s}^{\mathcal{O}}, \tilde{Z}_{s} + \alpha_{s}^{\mathcal{O}})\right) ds - \tilde{Z}_{s} dB_{s}, \quad \tilde{\Gamma}_{T} = G^{\mathcal{O}}_{s}$$

we then have

 $\Gamma_t \leq \Gamma_t^{\mathcal{O}}.$ 

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### Symmetrising 1

#### • Main messages and ideas:

- Averaging convex BSDEs increases solutions, because generator decreases by convexity.
- So averaging gives upper bounds but how to choose good set  ${\mathcal O}$  for averaging?
- Upper bound on  $\Gamma$  increases with **maximal eigenvalue** of  $\Lambda$ .
- So: reduce maximal eigenvalue by making A maximally symmetric ...
- $\bullet$   $\ldots$  hence choose for  ${\cal O}$  the permutation group  ${\rm Perm.}$

• Notations: 
$$G^{\text{sym}} := \frac{1}{n!} \sum_{u \in \text{Perm}} G \circ U_t$$
,  
 $\alpha^{\text{sym}} := \frac{1}{n!} \sum_{u \in \text{Perm}} u'(\alpha \circ U_t), \ \chi^{\text{sym}} := \frac{1}{n!} \sum_{u \in \text{Perm}} \chi \circ U_t$ .

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### Symmetrising 2

• Corollary: Assume A is diagonal and set

$$d_t := \left\| rac{1}{n} \sum\limits_{j=1}^n \max\limits_{u \in \operatorname{Perm}} (\Lambda^{ij}_s \circ U_t) 
ight\|_\infty$$

Then (upper bound from symmetrised setting)

$$\Gamma_t \leq -d_t \log E \bigg[ \exp \left( -G^{\text{sym}} + \int_t^T \alpha_s^{\text{sym}} \, dB_s + \int_t^T \chi_s^{\text{sym}} \, ds \right)^{1/d_t} \bigg| \mathcal{F}_t \bigg].$$

Idea for proof: Combine averaging result for *O* = Perm with measure change result for *κ* ≡ 0 and use that RHS above is (by Jensen) increasing in the argument *d<sub>t</sub>*.

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### Generalisations

- Results can be **generalised** to some degree:
  - Can replace boundedness of *G*, *α*, *χ* by appropriate exponential moment conditions.
  - Can relax assumption that eigenvalues of Λ are bounded away from infinity.
  - Cannot relax assumption that eigenvalues of Λ are uniformly bounded away from 0.

• Hard question: How about other (more general) generators ?

Basics Model and BSDE Fixing problems

# Towards finance applications

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## Exponential utility indifference valuation

- Given: model S for discounted asset prices, class  $\Theta$  of allowed strategies, discounted payoff G.
- Wanted: valuation for G.
- Incomplete market: value depends on subjective preferences.
- Use exponential utility function  $U(x) = -\exp(-\gamma x)$ .
- **Utility indifference value**  $b_t$  for buying *G* at time *t*: implicitly defined by

$$\begin{aligned} & \underset{\theta \in \Theta}{\text{ess sup }} E\left[ U\left(x_t + \int_t^T \theta_u \, dS_u\right) \, \middle| \, \mathcal{F}_t \right] \\ & = \underset{\theta \in \Theta}{\text{ess sup }} E\left[ U\left(x_t - b_t + \int_t^T \theta_u \, dS_u + G\right) \, \middle| \, \mathcal{F}_t \right]. \end{aligned}$$

• Indifference, in terms of expected utility under optimal investment, between buying or not buying payoff.

Basics Model and BSDE Fixing problems

## Specific model

- Independent BMs W and  $W^{\perp}$  valued in  $\mathbb{R}^m$  and  $\mathbb{R}^n$ .
- Correlated Brownian motion

$$dY_s = R_s \, dW_s + \sqrt{I_{n \times n} - R_s R'_s} \, dW_s^{\perp}.$$

- Eigenvalues of *RR*<sup>'</sup> uniformly bounded away from 1.
- "Correlation matrix"  $\Lambda = \frac{1}{\gamma} (I_{n \times n} RR')^{-1}$  has  $\delta_t^{\min} \ge \frac{1}{\gamma}$ .

• Model for S (R<sup>m</sup>-valued) is

$$dS_s^j = S_s^j \mu_s^j \, ds + \sum_{k=1}^m S_s^j \sigma_s^{jk} \, dW_s^k.$$

- Filtration (**G**) generated by  $W, W^{\perp}$ .
- Notation: Sharpe ratio is  $\lambda := \sigma^{-1}\mu$ .
- Everything nicely bounded ...

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Basics Model and BSDE Fixing problems

## (Wrong) BSDE for indifference value

• Well-known result: maximal expected utility

$$V_t^G := \operatorname{ess\,sup}_{\pi \in \Pi} E\left[-\exp\left(-\gamma \int_t^T \pi'_u \sigma_u \, dW_u - \gamma G\right) \, \middle| \, \mathcal{G}_t\right]$$

satisfies  $V_t^{\mathcal{G}} = -\exp(-\gamma \check{\Gamma}_t)$  with quadratic BSDE

$$\check{\Gamma}_{s} = G - \int_{s}^{T} \left(\frac{\gamma}{2} |\check{Z}_{r}|^{2} - \hat{Z}_{r}'\lambda_{r} - \frac{1}{2\gamma} |\lambda_{r}|^{2}\right) dr$$
$$+ \int_{s}^{T} \hat{Z}_{r} dW_{r} + \int_{s}^{T} \check{Z}_{r} dW_{r}^{\perp}.$$

- — Hu/Imkeller/Müller (2005)
- Unique solution, nice properties, ... —
- — but BSDE does not have general form we need !
- **Problem:** Only second part  $\check{Z}$  of full vector  $Z = (\hat{Z}, \check{Z})$  appears in fully quadratic form.

Basics Model and BSDE Fixing problems

### Making our results applicable 1

• First approach: replace BSDE by

$$\begin{split} \check{\Gamma}_{s}^{\epsilon} &= G - \int_{s}^{T} \left( \frac{\gamma}{2} |\check{Z}_{r}^{\epsilon}|^{2} + \epsilon |\hat{Z}_{r}^{\epsilon}| - (\hat{Z}^{\epsilon})_{r}' \lambda_{r} - \frac{1}{2\gamma} |\lambda_{r}|^{2} \right) dr \\ &+ \int_{s}^{T} \hat{Z}_{r}^{\epsilon} dW_{r} + \int_{s}^{T} \check{Z}_{r}^{\epsilon} dW_{r}^{\perp} \end{split}$$

(note that missing fully quadratic term  $\epsilon |\hat{Z}|^2$  has been added).

• Theorem 4: Our desired solution  $\check{\Gamma}$  is given by

$$\check{\Gamma}_t = - \operatorname{ess inf ess inf log } E_{Q^{\kappa}} [\exp(-\gamma G_t^{\kappa,\epsilon}) | \mathcal{G}_t]^{1/\gamma}.$$

• Usefulness: Gives lower bounds for  $\check{\Gamma}$  and hence for  $V^G$  by choosing suitable  $\epsilon$  and  $\kappa$ .

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Basics Model and BSDE Fixing problems

## Making our results applicable 2

• Special case:  $\kappa = \lambda$  gives  $Q^{\kappa} = \hat{P}$  (the minimal martingale measure) and

$$\check{\Gamma}_t \geq -\log E_{\hat{P}}\left[\exp\left(-\gamma G - \frac{1}{2}\int_t^T |\lambda_r|^2 \, dr\right) \, \middle| \, \mathcal{G}_t\right]$$

### • $\longrightarrow$ Zariphopoulou (2001), ...

 Remark: Can use projection results to get upper bounds for V<sup>G</sup>.

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## Nontradable payoffs and symmetrisation 1

### • Assume that

- G is  $\mathcal{F}_T^Y$ -measurable
- $\lambda = \sigma^{-1} \mu$  is  $I\!\!F^Y$ -predictable
- R is  $I\!\!F^{Y}$ -predictable

### • Interpretation:

- Think of Y as **nontradable factor** (process).
- Payoff G only depends on factor (e.g. variance swap).
- Sharpe ratio only depends on factor (e.g. stochastic volatility model).
- Note that S and Y can have stochastic correlation via R.
- Correlations only depend on factor.
- **Comment:** Looks restrictive but most literature has all parameters nonrandom and constant in time!

< 47 ▶

Basics Model and BSDE Fixing problems

## Nontradable payoffs and symmetrisation 2

• Key point of assumptions: obtain  $V^{G} = -\exp(-\gamma\Gamma)$  with

$$\Gamma_s = G - \int_s^T \left( \frac{1}{2} Z'_r \Lambda_r^{-1} Z_r - Z'_r R_r \lambda_r - \frac{1}{2\gamma} |\lambda_r|^2 \right) dr + \int_s^T Z_r \, dY_r.$$

- Consequences:
  - **Technically:** Above BSDE falls now into our general framework, so can use all results and techniques.
  - Economically: Everything can be expressed in factor filtration.
- In particular: can use symmetrisation estimates.
- Limitations: needs technical conditions; competing impacts.

References The end

# **Some references**

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References The end

## Some references

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- Rouge/El Karoui (2000)
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- ... (other missing links)

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References The end

## The end (for now ...)

# Thank you for your attention !

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